Generative Adversarial Networks

ACTL3143 & ACTL5111 Deep Learning for Actuaries
Patrick Laub





Lecture Outline

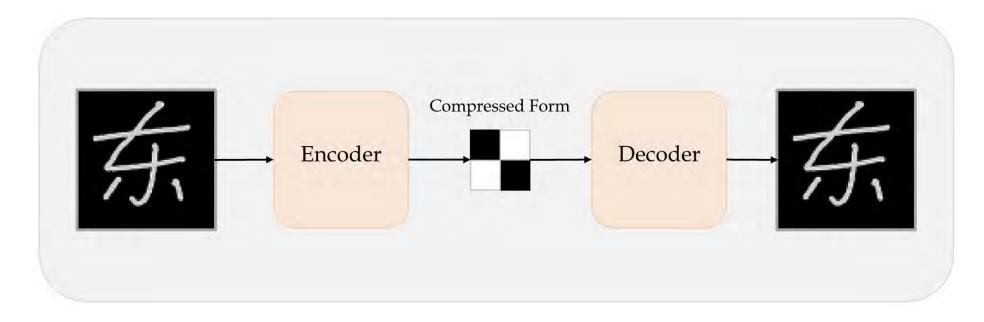
- Traditional GANs
- Training GANs
- Conditional GANs
- Image-to-image translation
- Problems with GANs
- Wasserstein GAN





Before GANs we had autoencoders

An autoencoder takes a data/image, maps it to a latent space via en encoder module, then decodes it back to an output with the same dimensions via a decoder module.



Schematic of an autoencoder.





GAN faces





Try out https://www.whichfaceisreal.com.





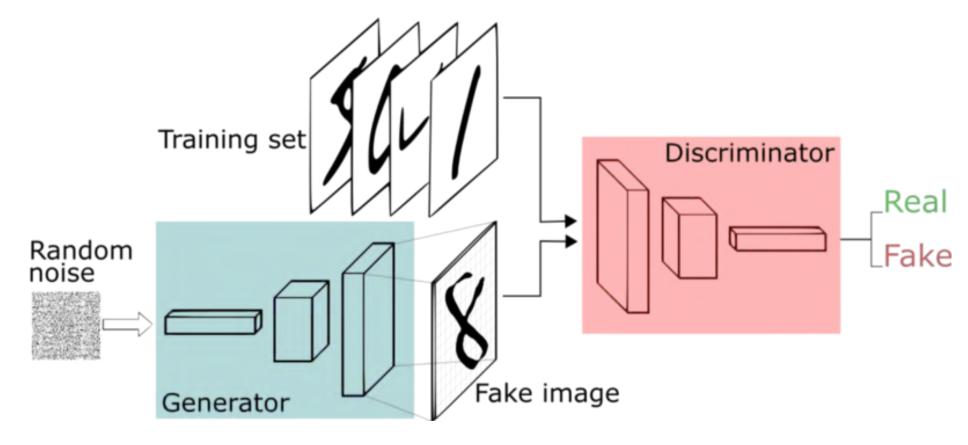
Example StyleGAN2-ADA outputs

Training a GAN from your Own Images: StyleGAN2 ADA





GAN structure

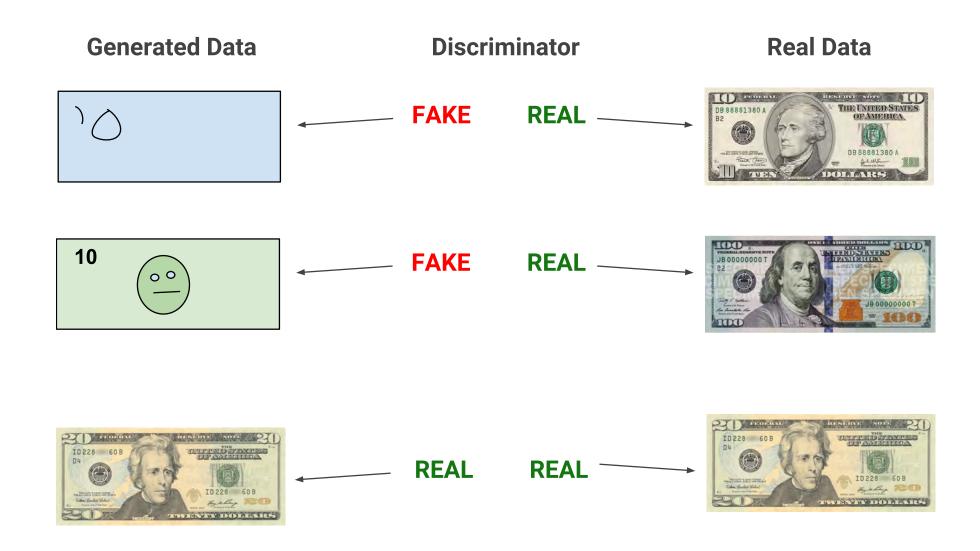


A schematic of a generative adversarial network.





GAN intuition







Intuition about GANs

- A forger creates a fake Picasso painting to sell to an art dealer.
- The art dealer assesses the painting.

How they best each other:

- The art dealer is given both authentic paintings and fake paintings to look at. Later on, the validity his assessment is evaluated and he trains to become better at detecting fakes. Over time, he becomes increasingly expert at authenticating Picasso's artwork.
- The forger receives an assessment from the art dealer everytime he gives him a fake. He knows he has to perfect his craft if the art dealer can detect his fake. He becomes increasingly adept at imitating Picasso's style.





Generative adversarial networks

- A GAN is made up of two parts:
 - Generator network: the forger. Takes a random point in the latent space, and decodes it into a synthetic data/image.
 - Discriminator network (or adversary): the expert. Takes a data/image and decide whether it exists in the original data set (the training set) or was created by the generator network.





Discriminator

```
lrelu = layers.LeakyReLU(alpha=0.2)

discriminator = keras.Sequential([
    keras.Input(shape=(28, 28, 1)),
    layers.Conv2D(64, 3, strides=2, padding="same", activation=lrelu),
    layers.Conv2D(128, 3, strides=2, padding="same", activation=lrelu),
    layers.GlobalMaxPooling2D(),
    layers.Dense(1)])

discriminator.summary()
```





Generator

```
latent_dim = 128
generator = keras.Sequential([
    layers.Dense(7 * 7 * 128, input_dim=latent_dim, activation=lrelu),
    layers.Reshape((7, 7, 128)),
    layers.Conv2DTranspose(128, 4, strides=2, padding="same", activation=lrelu),
    layers.Conv2DTranspose(128, 4, strides=2, padding="same", activation=lrelu),
    layers.Conv2D(1, 7, padding="same", activation="sigmoid")])
generator.summary()
```



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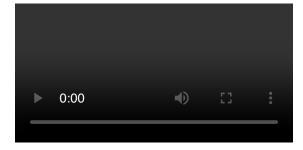
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GAN cost functions



The loss function à la 3Blue1Brown.





GAN - Schematic process

First step: Training discriminator:

- Draw random points in the latent space (random noise).
- Use *generator* to generate data from this random noise.
- Mix generated data with real data and input them into the discriminator. The training targets are the correct labels of real data or fake data. Use discriminator to give feedback on the mixed data whether they are real or synthetic. Train discriminator to minimize the loss function which is the difference between the discriminator's feedback and the correct labels.





GAN - Schematic process II

Second step: Training *generator*:

- Draw random points in the latent space and generate data with *generator*.
- Use *discriminator* to give feedback on the generated data. What the generator tries to achieve is to fool the *discriminator* into thinking all generated data are real data. Train *generator* to minimize the loss function which is the difference between the discriminator's feedback and the desired feedback: "All data are real data" (which is not true).





GAN - Schematic process III

- When training, the discriminator may end up dominating the generator because the loss function for training the discriminator tends to zero faster. In that case, try reducing the learning rate and increase the dropout rate of the discriminator.
- There are a few tricks for implementing GANS such as introducing stochasticity by adding random noise to the labels for the discriminator, using stride instead of pooling in the discriminator, using kernel size that is divisible by stride size, etc.





Train step

```
1 # Separate optimisers for discriminator and generator.
2 d optimizer = keras.optimizers.Adam(learning rate=0.0003)
 3 g optimizer = keras.optimizers.Adam(learning rate=0.0004)
   # Instantiate a loss function.
   loss fn = keras.losses.BinaryCrossentropy(from logits=True)
   atf.function
   def train step(real images):
     # Sample random points in the latent space
     random latent vectors = tf.random.normal(shape=(batch size, latent dim))
     # Decode them to fake images
     generated_images = generator(random_latent_vectors)
     # Combine them with real images
14
15
     combined_images = tf.concat([generated_images, real_images], axis=0)
16
     # Assemble labels discriminating real from fake images
17
     labels = tf.concat([
      tf.zeros((batch size, 1)),
19
20
       tf.ones((real images.shape[0], 1))], axis=0)
21
     # Add random noise to the labels - important trick!
22
     labels += 0.05 * tf.random.uniform(labels.shape)
23
24
25
     # Train the discriminator
     with tf.GradientTape() as tape:
26
       prodictions - discriminator(combined images)
```





Grab the data

```
# Prepare the dataset.
# We use both the training & test MNIST digits.
batch_size = 64

(x_train, _), (x_test, _) = keras.datasets.mnist.load_data()
all_digits = np.concatenate([x_train, x_test])
all_digits = all_digits.astype("float32") / 255.0

all_digits = np.reshape(all_digits, (-1, 28, 28, 1))
dataset = tf.data.Dataset.from_tensor_slices(all_digits)
dataset = dataset.shuffle(buffer_size=1024).batch(batch_size)

# In practice you need at least 20 epochs to generate nice digits.
epochs = 1
save_dir = "./"
```



Train the GAN



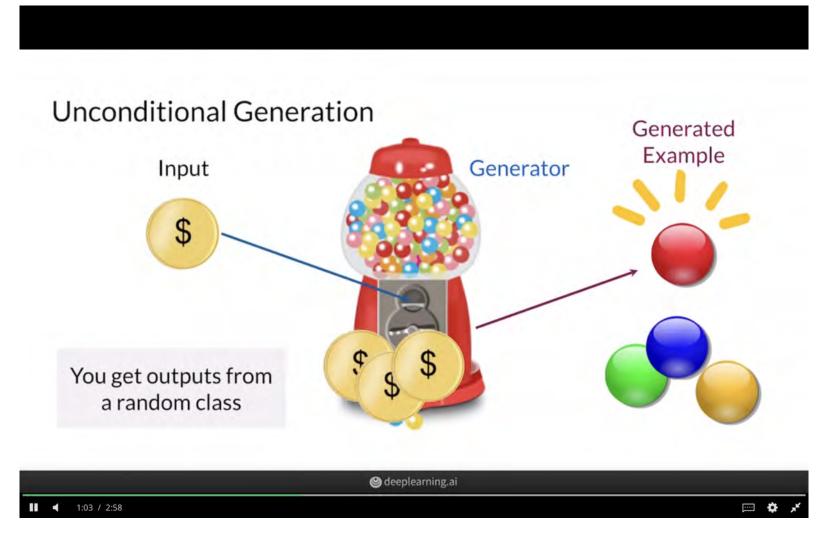


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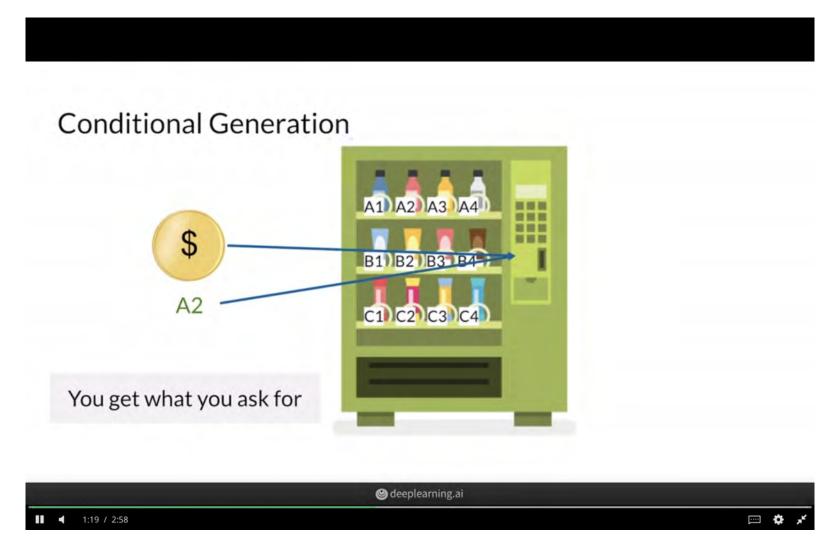


Unconditional GANs



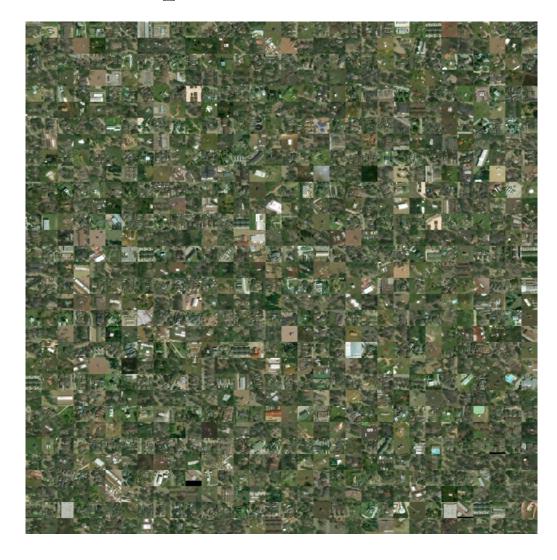


Conditional GANs





Hurricane example data



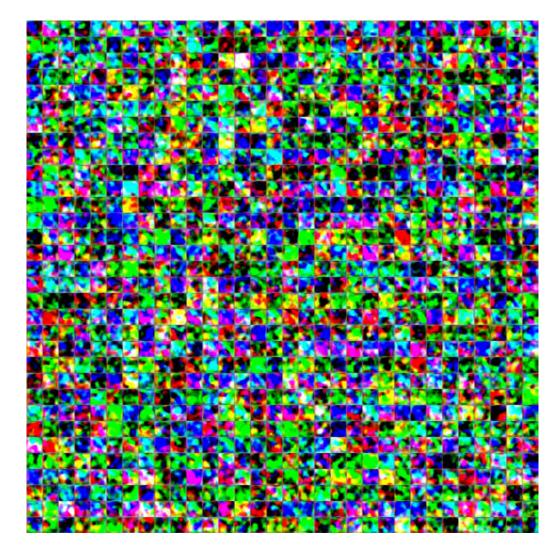








Hurricane example



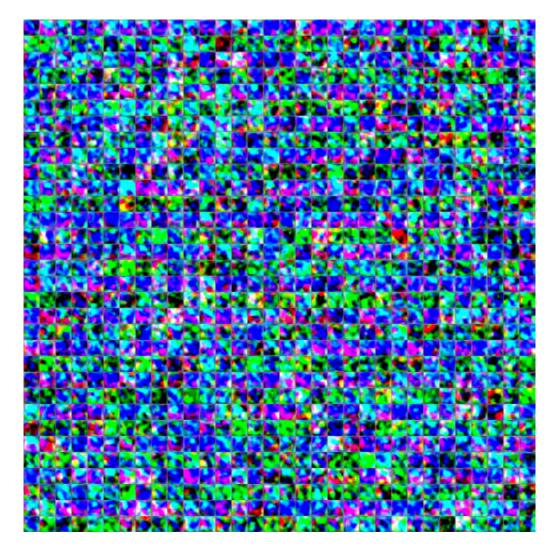








Hurricane example (after 54s)









Hurricane example (after 21m)



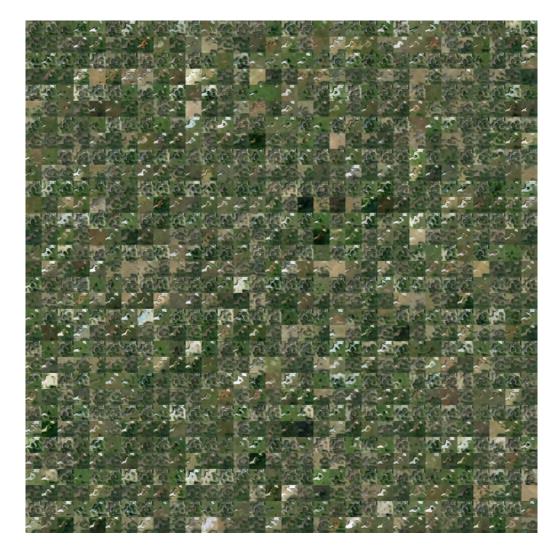








Hurricane example (after 47m)











Hurricane example (after 4h10m)











Hurricane example (after 14h41m)











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Example: Deoldify images #1



A deoldified version of the famous "Migrant Mother" photograph.





Example: Deoldify images #2



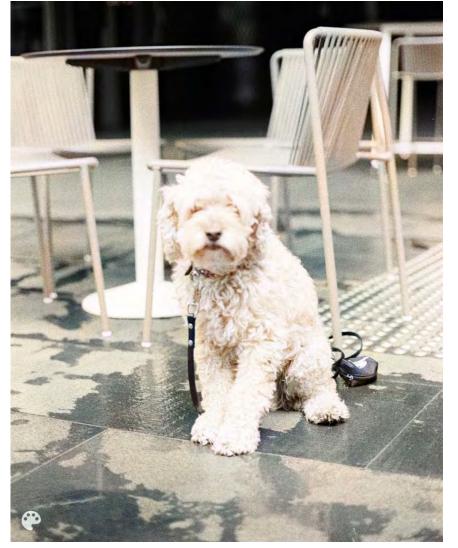
A deoldified Golden Gate Bridge under construction.





Example: Deoldify images #3









Explore the latent space

Finding Myself in a trained StyleGAN2 ADA





Generator can't generate everything





Target Projection





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They are slow to train

StyleGAN2-ADA training times on V100s (1024x1024):

GPUs	1000 kimg	25000	sec /	GPU	CPU mem
		kimg	kimg	mem	
1	1d 20h	46d 03h	158	8.1 GB	5.3 GB
2	23h 09m	24d o2h	83	8.6 GB	11.9 GB
4	11h 36m	12d 02h	40	8.4 GB	21.9 GB
8	5h 54m	6d 03h	20	8.3 GB	44.7 GB





Uncertain convergence

Converges to a Nash equilibrium.. if at all.

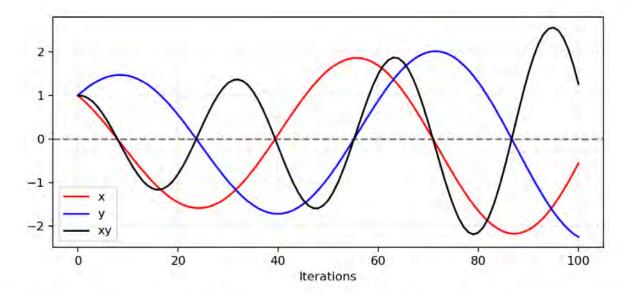


Figure 3: A simulation of our example for updating x to minimize xy and updating y to minimize -xy. The learning rate $\eta = 0.1$. With more iterations, the oscillation grows more and more unstable.

Analogy of minimax update failure.





Mode collapse

```
10k steps
                              100k steps
```

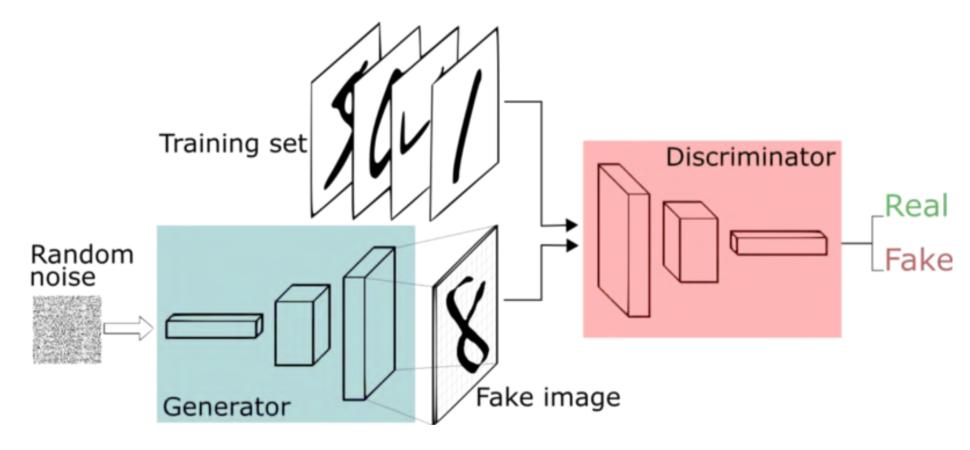
```
int getRandomNumber()
{
    return 4; // chosen by fair dice roll.
    // guaranteed to be random.
}
```

Example of mode collapse





Generation is harder



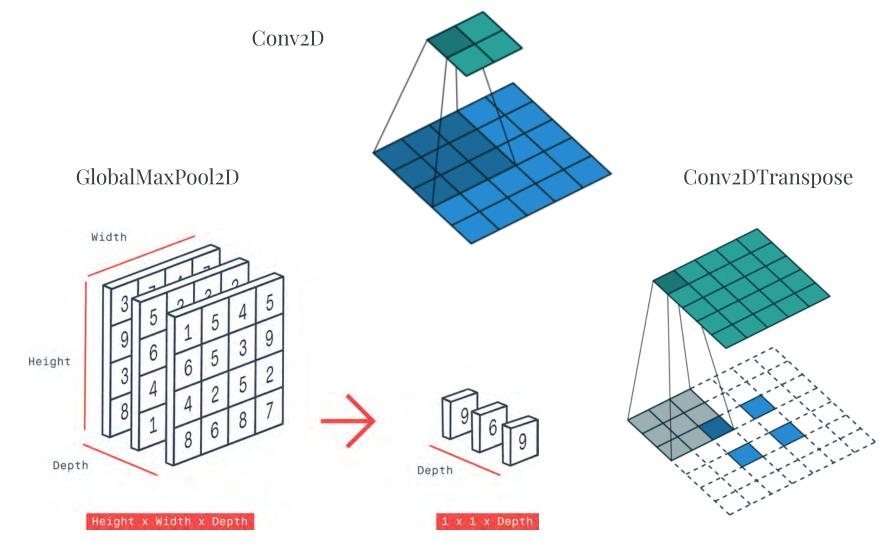
A schematic of a generative adversarial network.

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3 g_optimizer = keras.optimizers.Adam(learning_rate=0.0004)
```

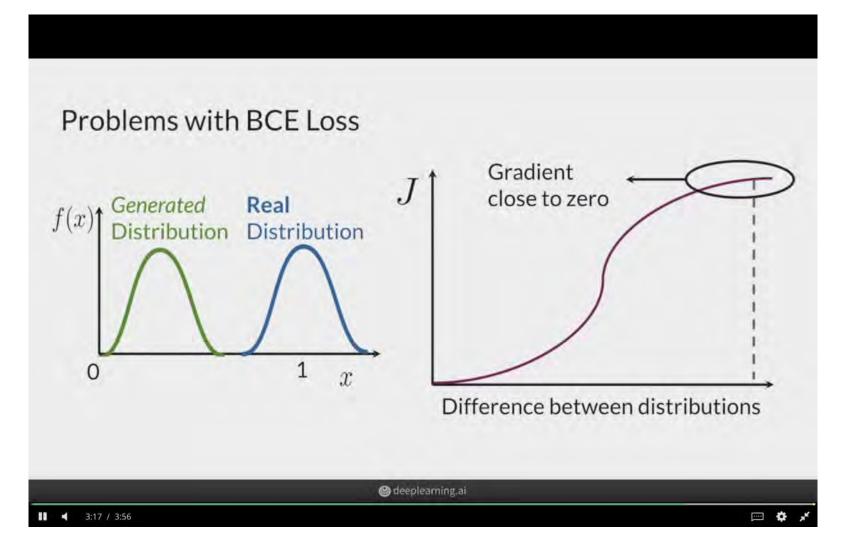




Advanced image layers



Vanishing gradients (I)



When the discriminator is too good, vanishing gradients





Vanishing gradients (II)

4.3 Vanishing Gradient

When the discriminator is perfect, we are guaranteed with $D(x) = 1, \forall x \in p_r$ and $D(x) = 0, \forall x \in p_g$. Therefore the loss function L falls to zero and we end up with no gradient to update the loss during learning iterations. Fig. 5 demonstrates an experiment when the discriminator gets better, the gradient vanishes fast.

As a result, training a GAN faces an dilemma:

- If the discriminator behaves badly, the generator does not have accurate feedback and the loss function cannot represent the reality.
- If the discriminator does a great job, the gradient of the loss function drops down to close to zero and the learning becomes super slow or even jammed.

This dilemma clearly is capable to make the GAN training very tough.

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Vanishing gradients





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We're comparing distributions

Trying to minimise the distance between the *distribution of generated* samples and the *distribution of real data*.

Vanilla GAN is equivalent to minimising the Jensen–Shannon Divergence between the two.

An alternative distance between distributions is the *Wasserstein distance*.





Discriminator Critic

Critic D: Input $\to \mathbb{R}$ how "authentic" the input looks. It can't discriminate real from fake exactly.

Critic's goal is

$$\max_{D\in \mathrm{D}} \mathbb{E}[D(X)] - \mathbb{E}[D(G(Z))]$$

where we D is space of 1-Lipschitz functions. Either use *gradient clipping* or penalise gradients far from 1:

$$\max_D \mathbb{E}[D(X)] - \mathbb{E}[D(G(Z))] + \lambda \mathbb{E}[(\left|\left|\nabla D\right|\right| - 1)^2].$$





Schematic

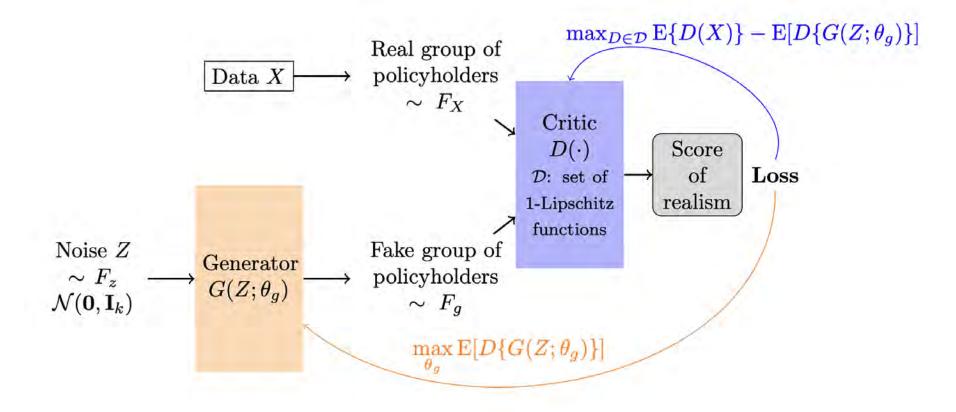


Figure 1: WGAN Schema. The arrows represent the flow of the training process.







Links

- Dongyu Liu (2021), TadGAN: Time Series Anomaly Detection Using Generative Adversarial Networks
- Jeff Heaton (2022), GANs for Tabular Synthetic Data Generation (7.5)
- Jeff Heaton (2022), GANs to Enhance Old Photographs Deoldify (7.4)



